

QC

**PROFESSIONAL STANDARD OF THE PEOPLE'S
REPUBLIC OF CHINA**

中华人民共和国汽车行业标准

QC/T 480-1999

**Criterion thresholds and evaluation of controllability and
stability for automobiles**

汽车操纵稳定性指标限值与评价方法

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Criterion thresholds and evaluation of controllability and stability for automobiles

汽车操纵稳定性指标限值与评价方法

QC/T 480-1999

Replaces GB/T 13047-91

1 Subject and scope of application

This standard specifies the criterion thresholds and evaluation of controllability and stability for automobiles.

This standard applies to vehicles running on highways and urban roads. The vehicles running on off-roads may be handled with reference to it.

2 Steady-state cornering test

2.1 This test is evaluated and scored with three indicators including lateral acceleration at neutral steering point, a_n , degree of understeering U , and roll rate of autobody K_ϕ .

2.2 See Table 1 for the lower limit value a_{n60} , U_{60} and $K_{\phi60}$, along with the upper limit values a_{n100} , U_{100} and $K_{\phi100}$ with respect to a_n , U and K_ϕ .

Table 1

Model	Indicators					
	a_{n60} m/s ²	a_{n100} m/s ²	U_{60} (°)(m/s ²)	U_{100} (°)(m/s ²)	$K_{\phi60}$ (°)(m/s ²)	$K_{\phi100}$ (°)(m/s ²)
Cars, passenger buses, and trucks with a maximum total mass not greater than 2.5 t	5.00	9.80	1.00 0.60 ¹⁾	0.40 0.24 ¹⁾	1.20	0.70
Passenger buses and trucks with a maximum total mass greater than 2.5 t but not great than 6 t	4.00	8.00	1.20	0.50		
Passenger buses and trucks with a maximum total mass greater than 6 t	3.00	6.00			1.20 1.40 ²⁾	

NOTES

- 1) For the vehicles running at maximum speed greater than 160 km/h.
- 2) For the passengers buses with a maximum total mass greater than 9 t.

2.3 The lateral acceleration at neutral steering point, a_n , is defined as the lateral acceleration at point that the slope is zero on the curve of the difference of sideslip angles between the front axle and the rear axle vs. the lateral acceleration. Within the lateral acceleration range tested, where no neutral steering point is present, the value of a_n is predicted in generalized least squares (least square method) as the fitting curve of cubic polynomial without constant term.

2.3.1 The lateral acceleration at neutral steering point, a_n , is evaluated and scored according to Equation (1).

$$N_{a_n} = 60 + \frac{40}{a_{n100} - a_{n60}} \bullet (a_n - a_{n60}) \dots\dots\dots (1)$$

where

N_{a_n} is the value of the evaluation and score of lateral acceleration at neutral steering point;

a_n is the test value, in m/s², of the lateral acceleration at neutral steering point;

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